# TRIMBLE MX2 MOBILE MAPPING SYSTEM

#### **KEY FEATURES**

**High performance** laser scanner captures fully synchronized point clouds

**Precision positioning** using tightly coupled GNSS and inertial referencing system

**Rugged, reliable** and lightweight design with low power consumption

Deploys on **all sizes** of onand off-road vehicles

**Use with Trimble Trident** software for data capture, extraction and analysis



# VERSATILE MOBILE MAPPING FOR GEOSPATIAL SURVEYS

The Trimble MX2 is a vehicle-mounted mobile mapping system which combines high resolution laser scanning and precise positioning to collect geo-referenced point clouds for a wide range of requirements. The system can be rapidly deployed onto on- and off-road. vehicles of all sizes, and significantly reduces project field time and operator skill levels compared to traditional techniques. The MX2 is supplied with Trimble's proven Trident software to rapidly extract and analyze the raw data to turn it into useful geospatial intelligence.

#### TRIMBLE MX2 TECHNOLOGY

The system has three main elements:

#### **Sensor Head**

A compact, lightweight, and rugged sensor package designed to be mounted on vehicles of all sizes. It contains one or two laser heads and a combined Trimble Applanix GNSS and inertial geo-referencing module for precise positioning. The dual head system uses a 'butterfly' LiDAR configuration to minimize shadowing. The sensor head can be rapidly installed in minutes and does not need a dedicated vehicle.

#### **Operator Console**

System control and data recording functions are provided by a ruggedized laptop PC running Trimble® Trident™ Capture software. This presents a clear, intuitive user interface, allowing the operator to rapidly set system parameters and manage data recording.

# **ANALYSIS SOFTWARE**

To quickly transform point clouds into geospatial intelligence, the system includes the proven Trimble Trident software suite. Trident Imaging Hub is available with the system and offers robust object positioning, measurement, and data layer creation, and is ideal for the analysis of mobile laser scanner data and geo-referenced imagery. The optional Trident Factory software enables high levels of automation and is optimized for more complex projects. For postprocessing options, the powerful Applanix POSPac MMS software is supplied.

# HIGH PRODUCTIVITY CAPTURE AND ANALYSIS

Capable of collecting up to 72,000 points per second in its dual scanner configuration, the system offers high levels of accuracy due to the performance of its Trimble Applanix GNSS/inertial reference technology. The highly efficient, end-to-end workflow is based on Trimble's 'Collect, Extract, Analyze' methodology, and enables detailed 3D infrastructure geometries to be captured in a single pass and rapidly processed. The system is characterized by operational flexibility, ease-of-use, high productivity, and excellent performance—yet it offers a low cost of ownership.

#### **BENEFITS**

- Versatile system offers significant operational flexibility
- Outstanding performance and value with low cost of ownership
- Optimizes staff utilization and lowers skill requirements
- Reduces project timescales through fast deployment, data capture, and analysis
- Highly efficient, proven analysis workflows
- Enhances operational capabilities and expands market opportunities



# **TRIMBLE MX2 MOBILE MAPPING SYSTEM**

## PERFORMANCE AND SPECIFICATION

	System	
Operating temperature	−10 °C to +50 °C	
Power supply	12 V DC to 32 V DC	
Environmental rating	IP65	
Weight	Single laser head: 17 kg Dual laser head: 25 kg	
	Laser(s) sub-system	
Туре	Single or dual SLM-250 Class 1 lasers	
Range	Up to 250 m	
Accuracy	±1 cm at 50 m to Kodak white card <sup>5</sup>	
Scanner FOV	360 degrees	
Scan rate	Single laser head: 20 Hz (1200 rpm) Dual laser head: 2 x 20 Hz (1200 rpm)	
Maximum effective measurement rate	Single laser head: 36,000 points per second Dual laser head: 72,000 points per second	
Pulse rate	Single laser head: 36 kHz Dual laser head: 2 x 36 kHz	
Positioning sub-system <sup>6</sup> (RMS ERROR)		
Туре	Trimble AP20 GNSS-Inertial System	
Technology	Advanced Applanix IN-Fusion™ GNSS- Inertial integration technology	
# of GNSS channels	220	
Inertial Measurement Unit	Applanix IMU-42 (non ITAR) with 200 Hz Data Rate	
Azimuth Determination	2 GNSS antennas, Applanix GNSS Azimuth Measurement System tightly coupled with IMU data	
Position (m): No GNSS Outages <sup>3</sup> 1 km or 1 minute GNSS Outage <sup>3+4</sup>	0.02 – 0.05 (Postprocessed) <sup>1</sup> ; 0.02 – 0.10 (RTK) <sup>2</sup> 0.13 – 0.24 (Postprocessed) <sup>1</sup> ; 0.35 – 0.69 (RTK) <sup>2</sup>	
True Heading (deg): No GNSS Outages <sup>3</sup> 1 km or 1 minute GNSS Outage <sup>3+4</sup>	0.025 (Postprocessed) <sup>1</sup> ; 0.050 (RTK) <sup>2</sup> 0.030 (Postprocessed) <sup>1</sup> ; 0.070 (RTK) <sup>2</sup>	
Options	Distance Measuring Indicator (DMI)	

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Point Cloud viewing and navigation in 3D	3D Measurements		
Imaging Playback, Image and Point Cloud blending	Point Selection & Classification Tools		
Trajectory Import	Image Converter		
Camera/Laser Boresight Calibration	RGB Point Cloud Colorization		
Target Detection/Registration	SHP/DXF Import and Export		
Database connectivity	Point Cloud Export (optional by Class) in LAS 1.1/1.2/1.4 or csv		
Photogrammetric/Point Cloud Feature addition	Pavement Defects Report		
Trident Factory (optional)			
Surface modelling	Road Modeller (DTM, Cross sections, Profiles)		
Sign and Pole Detection	Horizontal/Vertical Line of Sight		
Edge Detection	Horizontal/Vertical Clearances		
Centerline Detection	Land XML Export		

Trident Imaging Hub

#### **OPTIONS**

Options			
Camera Sub-system	Resolution	30 MP (5 MP x 6 sensors)	
	Field of View	90% of full sphere	
	Spherical Distance	Calibrated from 2m to infinity	
	Operating Temperature	0 °C to +45 °C	
	Power Consumption	12 to 24 V, 13 W via GPIO	
	Weight	3.0 kg	
Analysis	Applanix POSPac MMS Trimble Trident Factory		
Positioning	Distance Measurement Indicator (DMI)		

- POSPac MMS.
  Applanix IN-Fusion Inertially-Aided RTK, typical results.
  With GAMS and 2m baseline between antennas.
  With DMI Option.
  1 sigma under calibration conditions.
  Typical performance in a standard road vehicle with appropriate initialization and dynamics). Actual results are dependent upon satellite configuration, atmospheric conditions and other environmental effects.

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